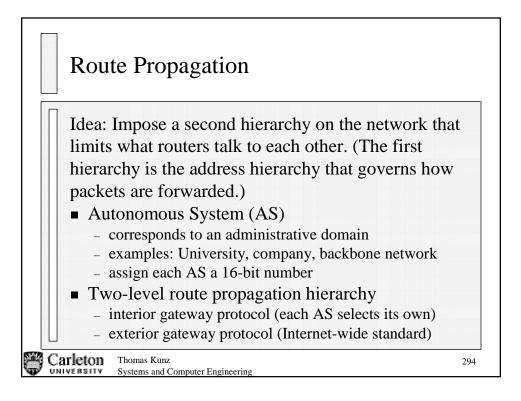
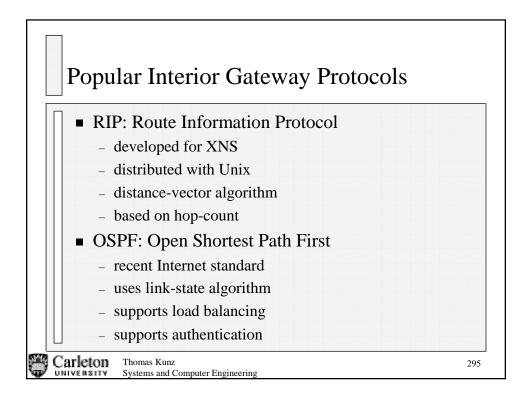
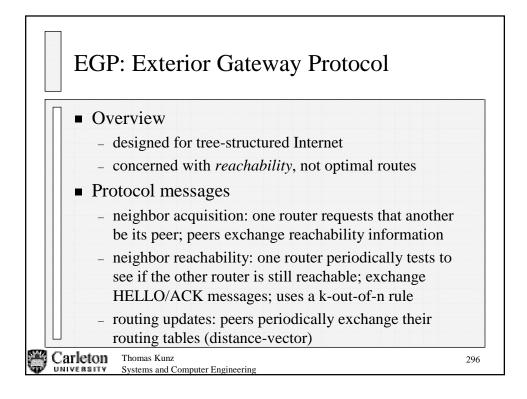
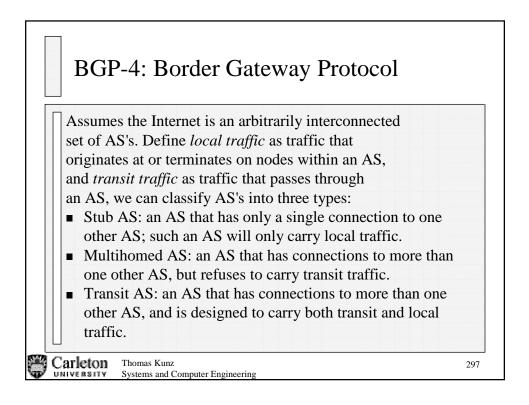


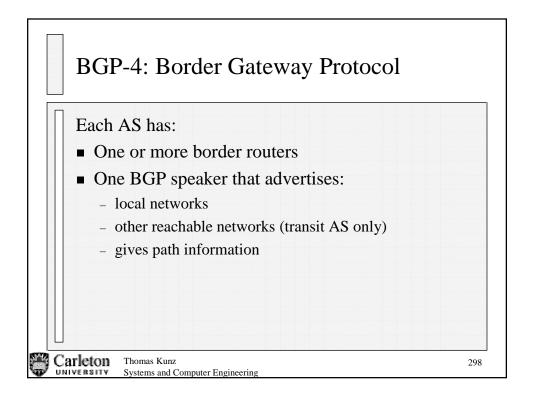
		ample			
Step	Confirmed	Tentative	Step	Confirmed	Tentativ
1.	(D,0,-)		5.	(D,0,-)	(A,12,C)
				(C,2,C)	
2.	(D,0,-)	(B,11,B)		(B,5,C)	
		(C,2,C)			
			6.	(D,0,-)	(A,10,C)
3.	(D,0,-)	(B,11,B)		(C,2,C)	
	(C,2,C)			(B,5,C)	
4.	(D,0,-)	(B,5,C)	7.	(D,0,-)	
	(C,2,C)	(A,12,C)		(C,2,C)	
				(B,5,C)	
				(A,10,C)	

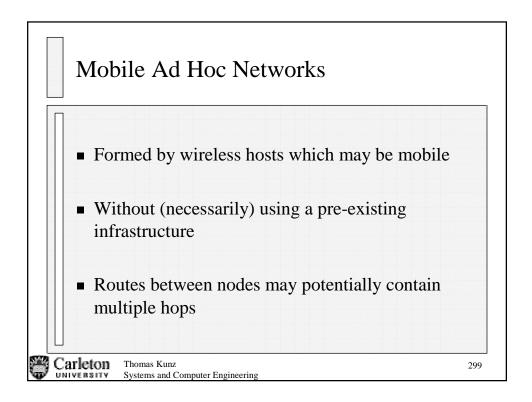


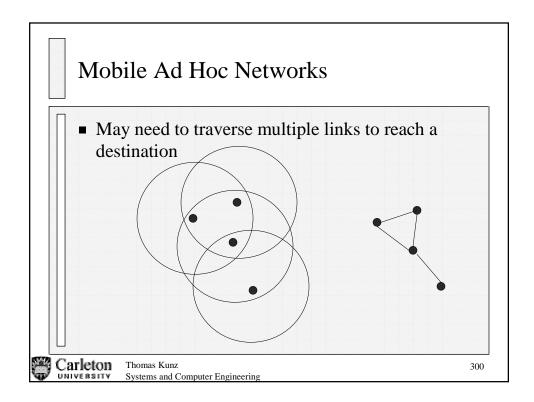


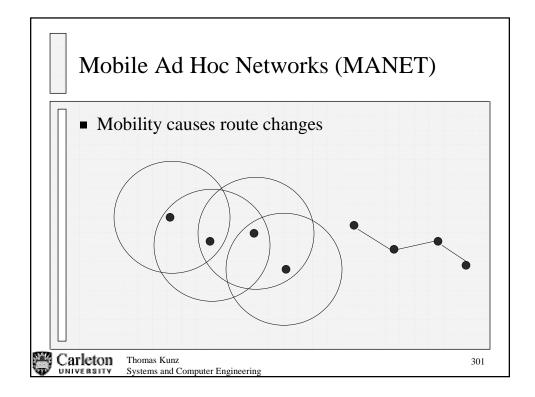


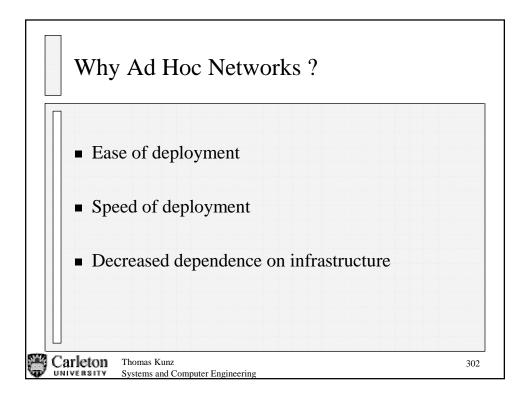


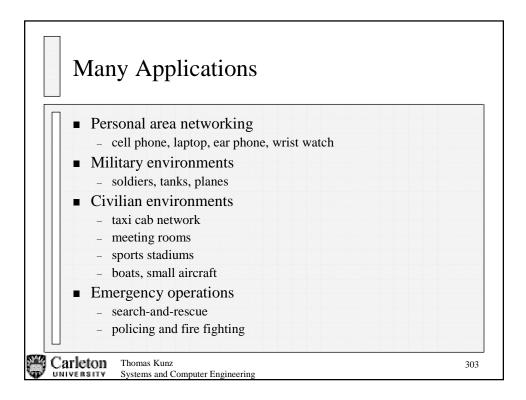


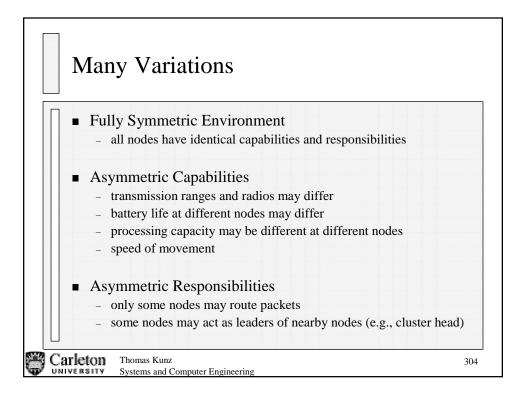


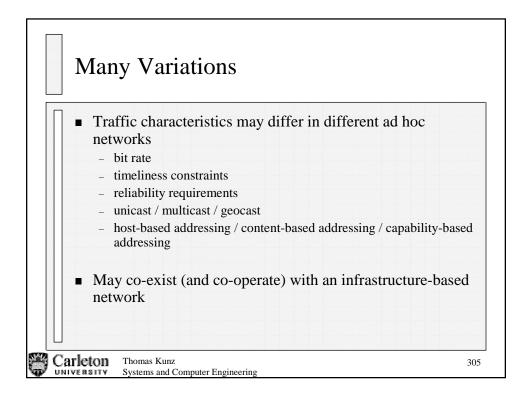


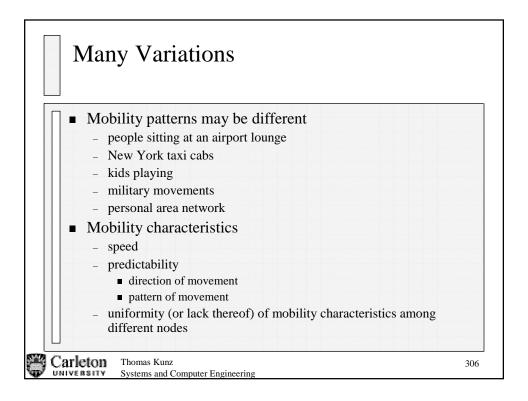


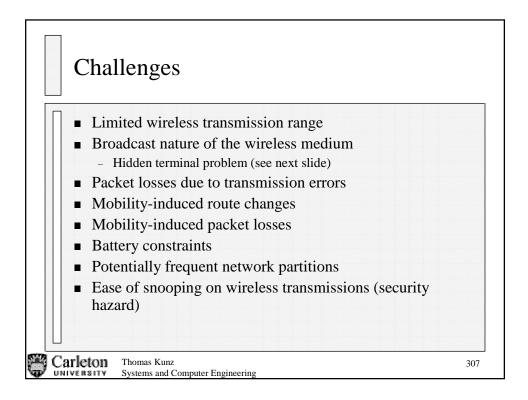


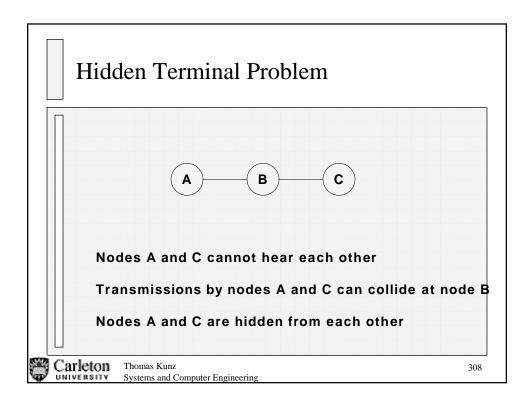


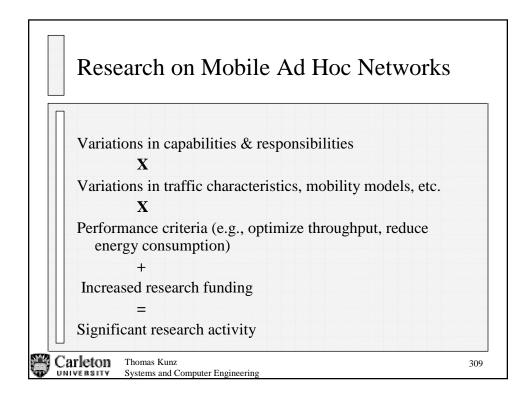


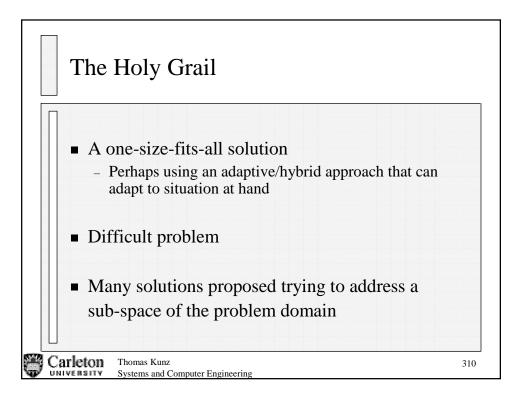


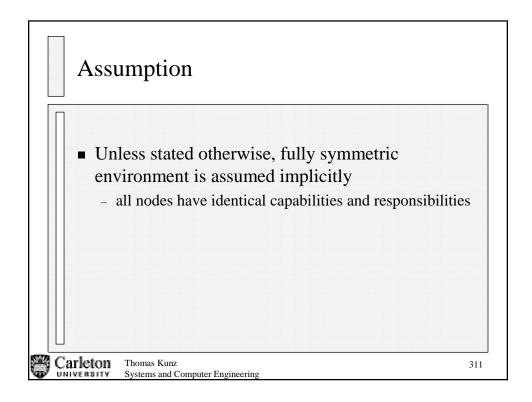


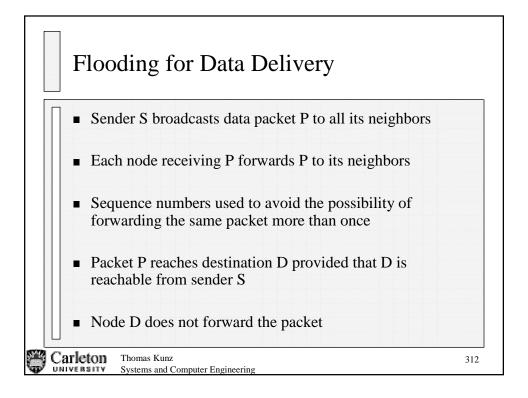


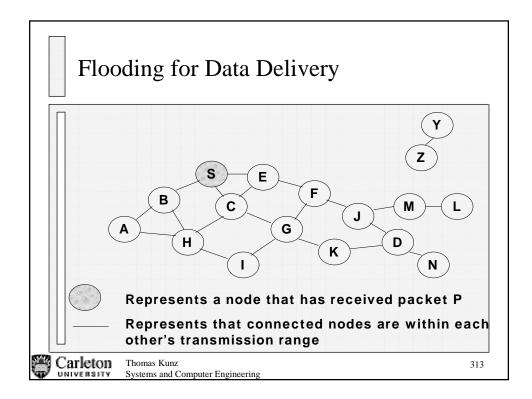


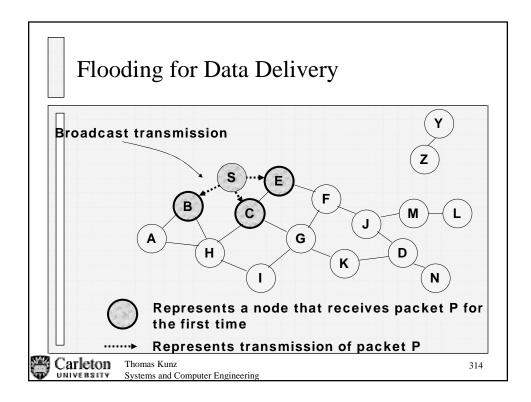


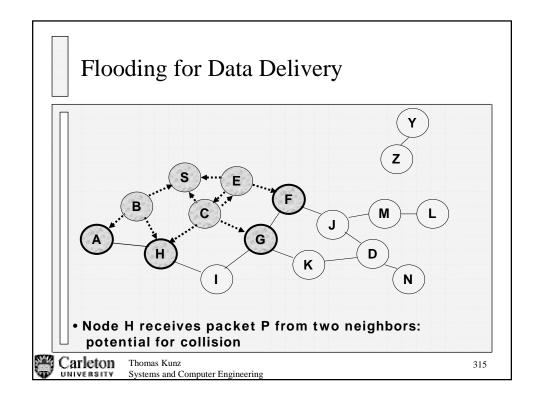


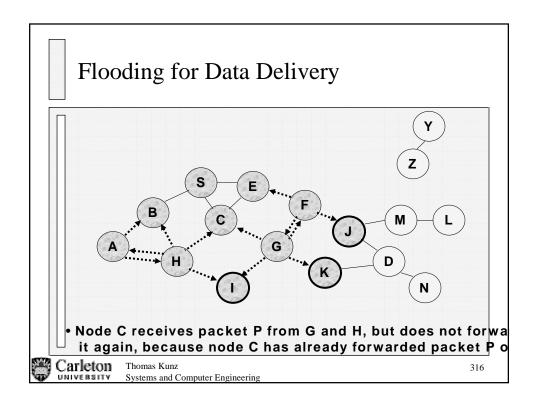


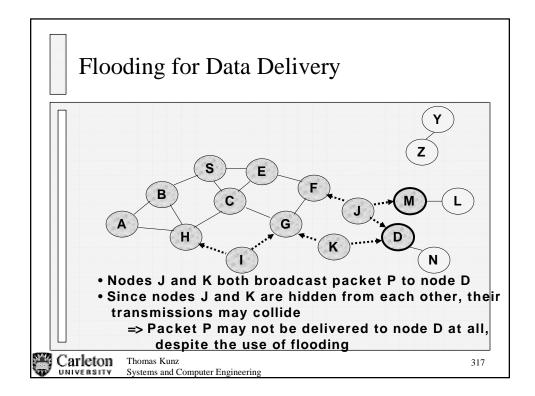


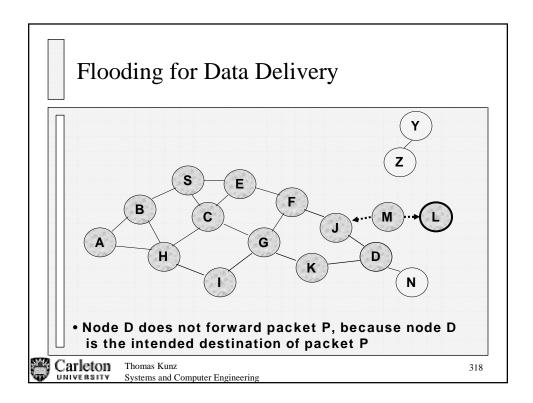


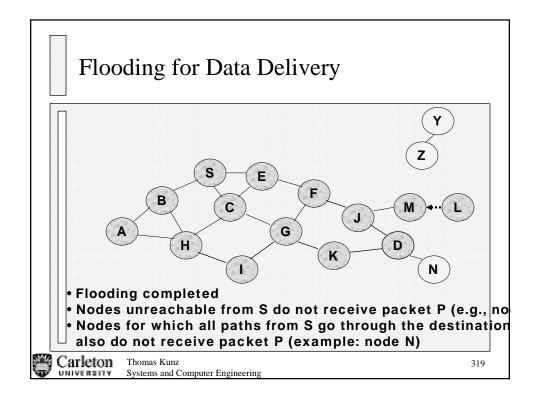


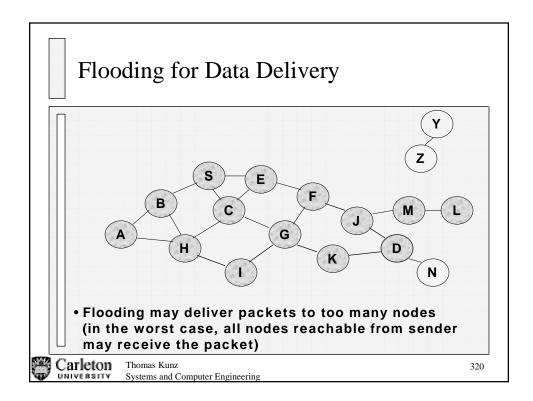


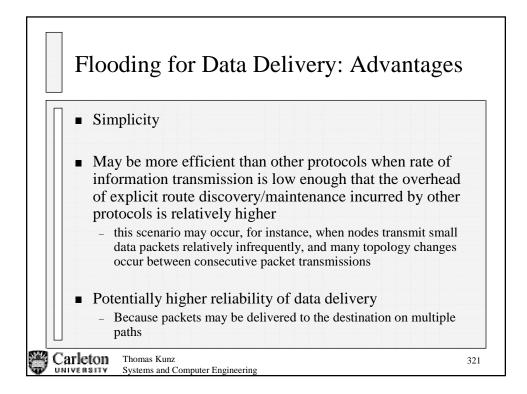


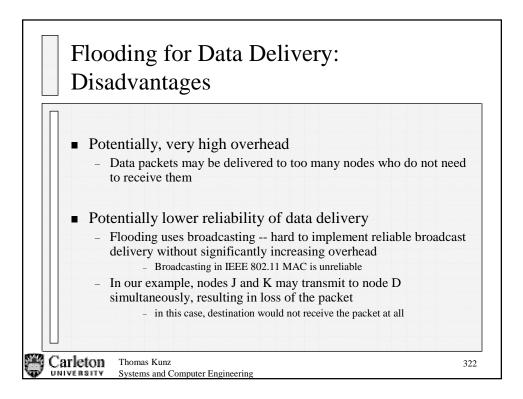


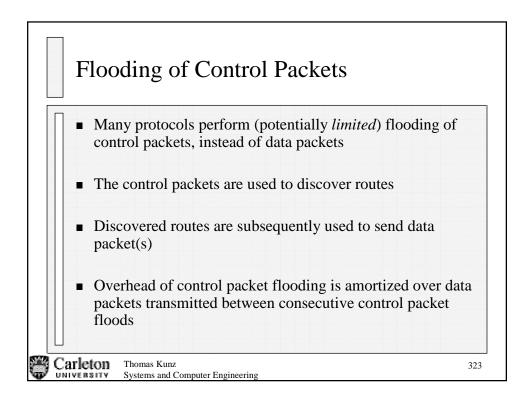


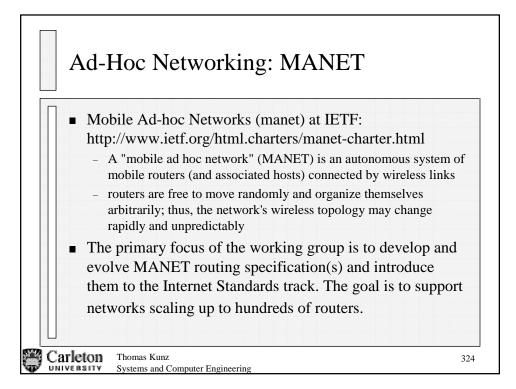


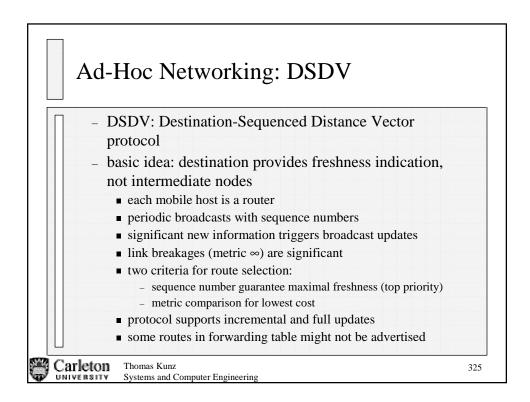




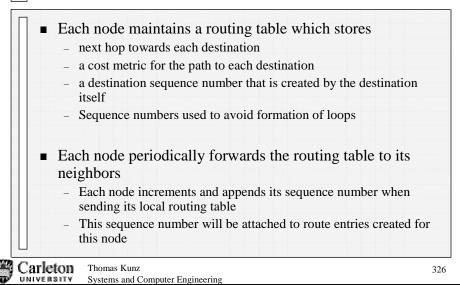


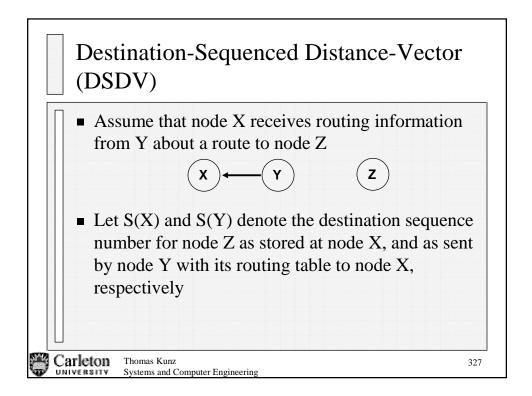


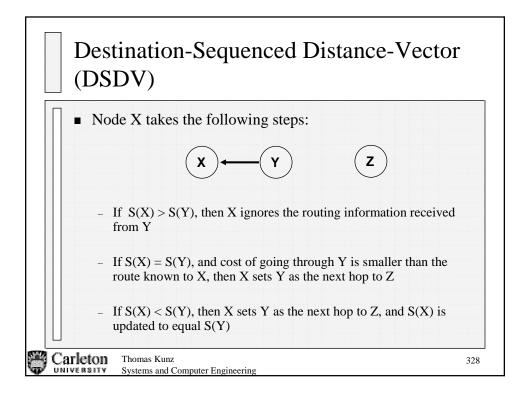


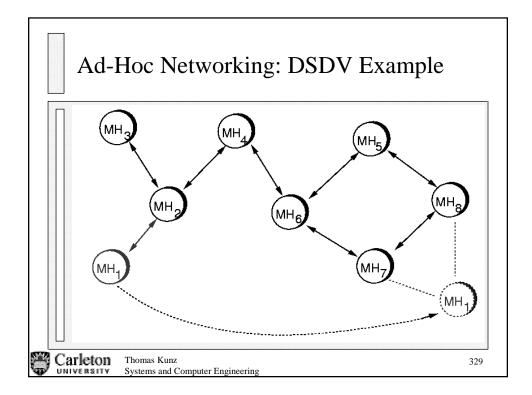


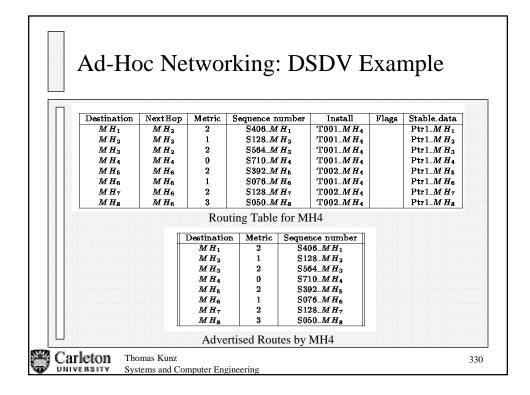
## Destination-Sequenced Distance-Vector (DSDV)





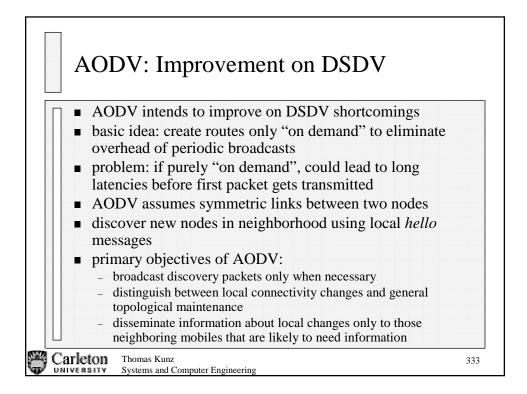


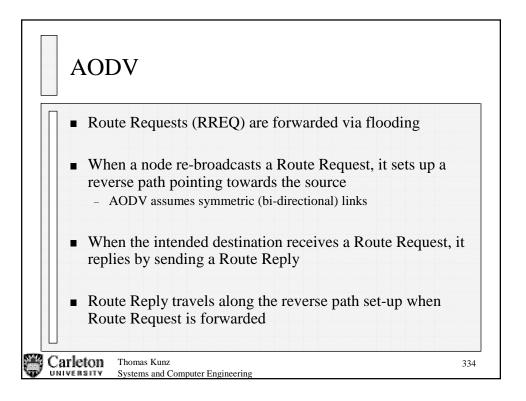


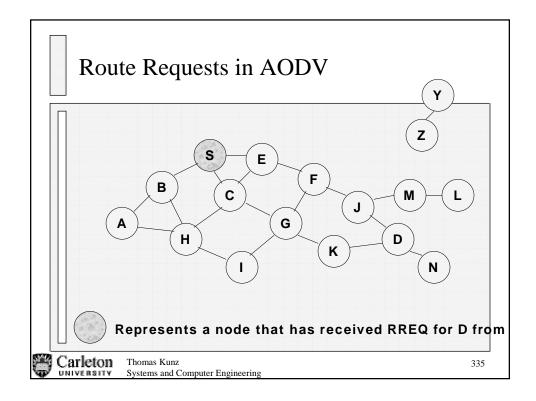


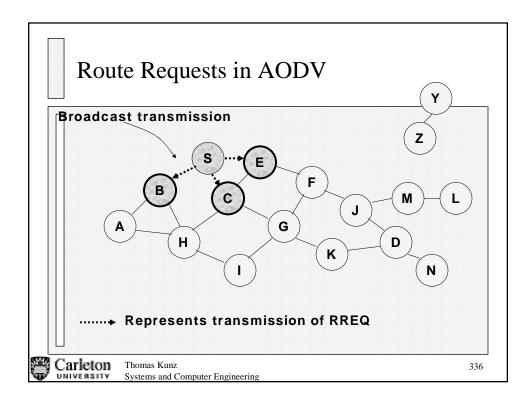
Ad-Ho	oc Ne	twor	king	: DS	SDV E	xar	nple
Destination	NextHop	Metric	Sequence	number	Install	Flags	Stable_data
$MH_1$	MH6	3	S516_MH1		T810_MHA	M	$Ptr1_MH_1$
$MH_2$	$MH_2$	1			T001_MH4		$Ptr1_MH_2$
$MH_3$	MH <sub>2</sub>	2	S674_MH <sub>3</sub>		T001_MH4		$Ptr1_MH_3$
$MH_4$	MH <sub>4</sub>	0	S820_MH4		T001_MH4		Ptr1_MH4
MH <sub>b</sub>	MH <sub>6</sub>	2	S502_MH <sub>5</sub>		T002_MH4		Ptr1_MH <sub>5</sub>
$MH_6$	$MH_6$	1	S186_MH <sub>6</sub>		T001_MH4		Ptr1_MH6
$MH_7$	MH <sub>6</sub>	2	S238_A	f H 7	T002_MH4		Ptr1_MH7
$MH_8$	$MH_6$	3	S160_A	1 H <sub>8</sub>	T002_MH4		$Ptr1_MH_8$
		Routing Destination	Table at Metric	Sequen	pdated) ce number $0_{MH_{A}}$		
		$MH_1$	3	$\begin{array}{c} {\rm S516\_MH_1} \\ {\rm S238\_MH_2} \\ {\rm S674\_MH_3} \\ {\rm S502\_MH_6} \\ {\rm S186\_MH_6} \\ {\rm S238\_MH_7} \end{array}$			
		$MH_2$	1				
		$MH_3$	2				
		$MH_{5}$	2				
		$MH_6$	1				
		$MH_7$	2				
		MH <sub>8</sub>	3	516	$0_M H_8$		
		Adver	tised Rou	tes by N	MH4		

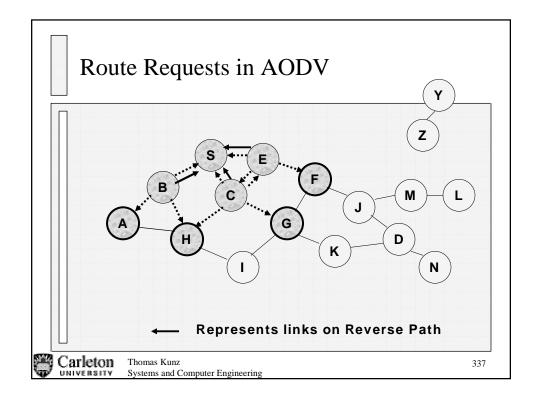
DS	SDV Evalua	ation		
	Routing Method	Looping	Internodal Coordination	Space Complexity
	Bellman Ford [2]	s/l	-	O(nd)
	Link State [8]	S	-	$O(n^2)$
	Loop-free BF [3]	s	-	O(nd)
	<b>RIP</b> [5]	s/l	-	O(n)
	Merlin Segall [9]	loop free	Required	O(nd)
	Jaffe Moss [6]	loop free	Required	O(nd)
	DSDV	loop free	-	O(n)
	OSDV good for smal			
• E	Brute-force approach	to larger n	etworks	
	<ul> <li>requires periodic ac information</li> </ul>	lvertisement	ts and global diss	emination of connectivity
	<ul> <li>each node has to ke</li> </ul>	ep complete	e list of routes	
Carleto	Thomas Kunz Systems and Compute	r Engineering		3

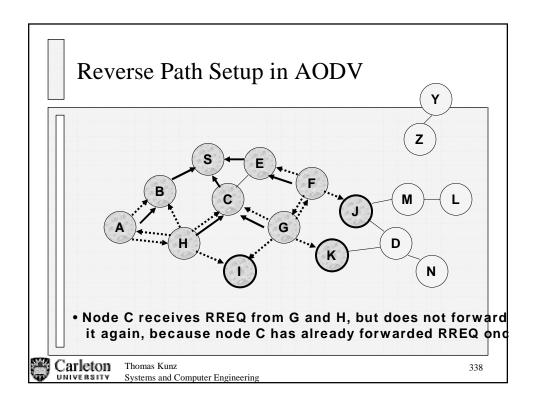


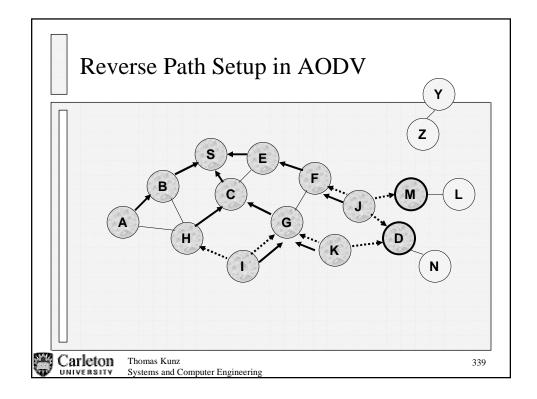


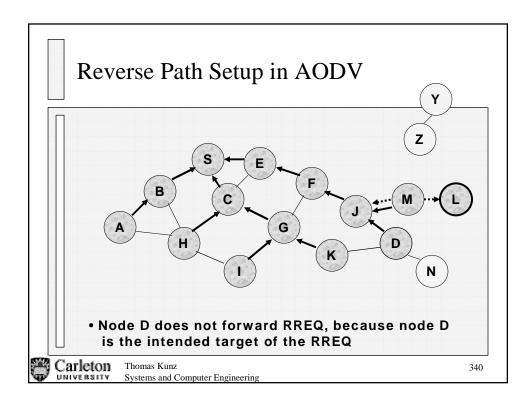


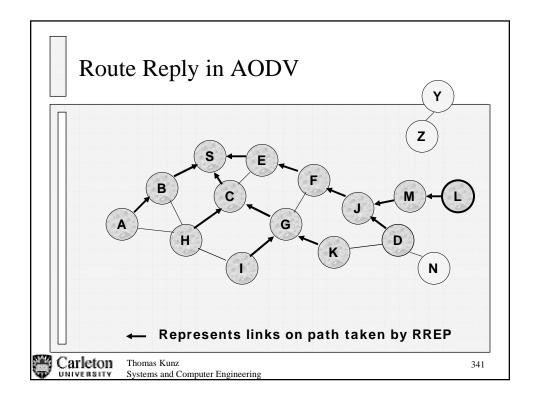


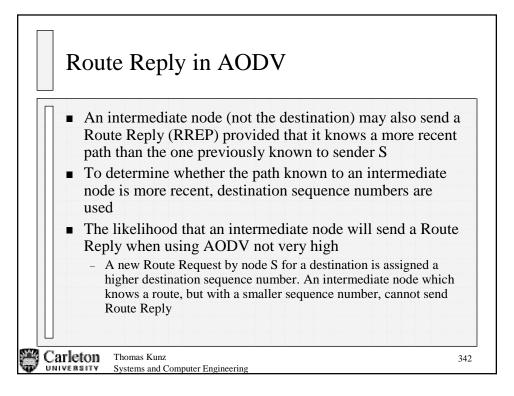


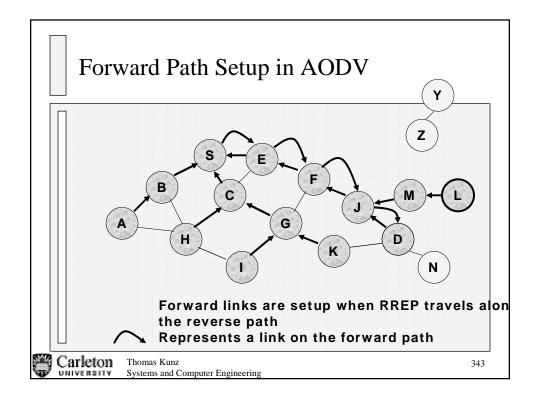


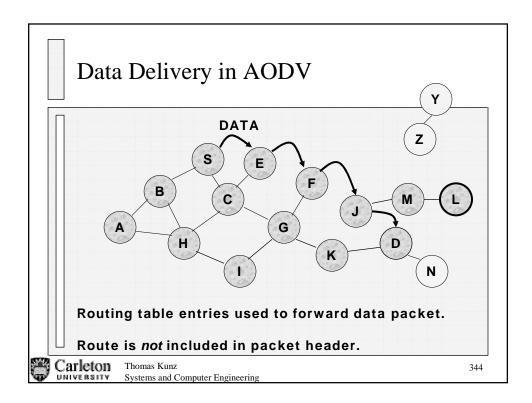


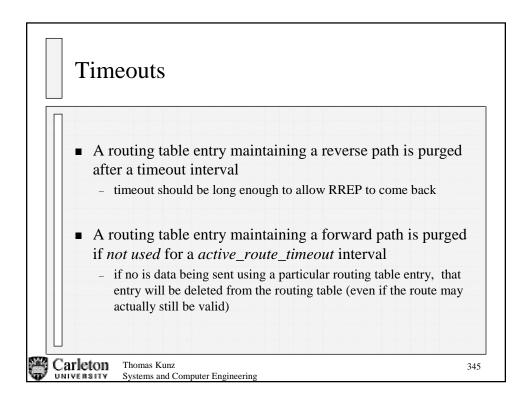


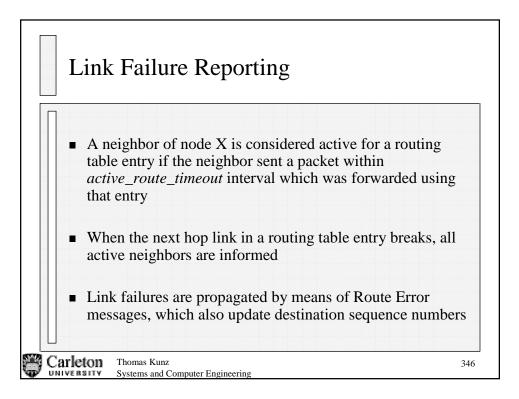


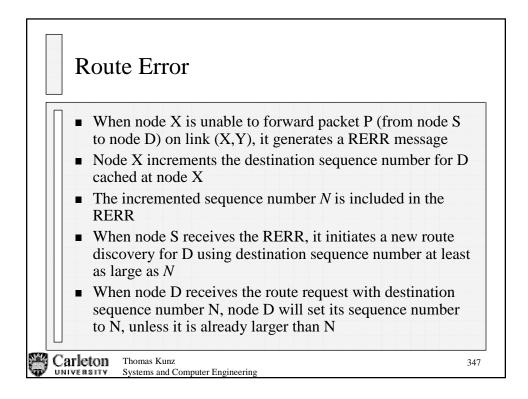


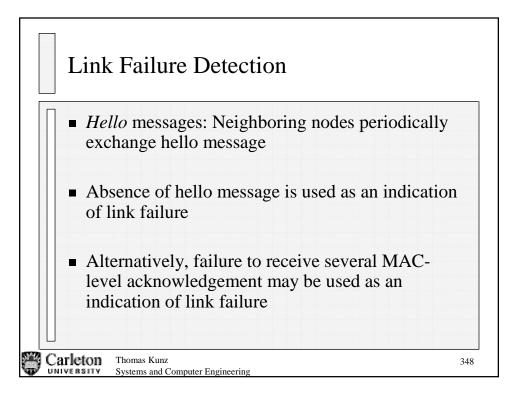


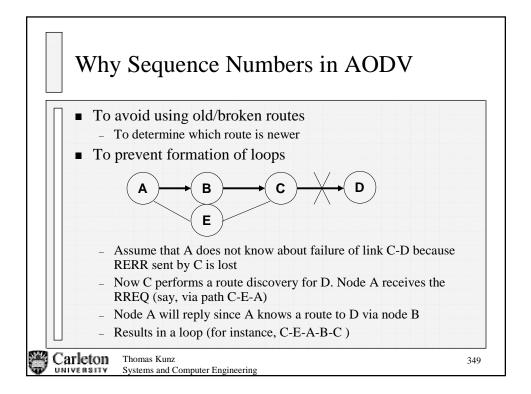


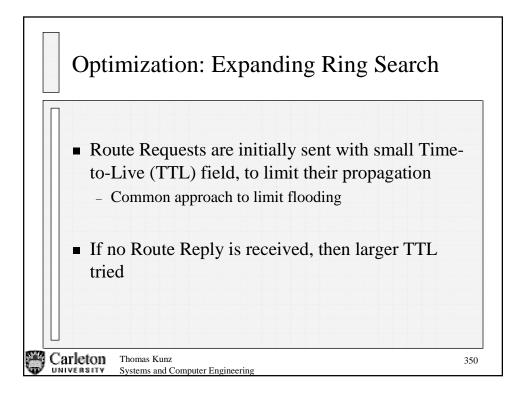


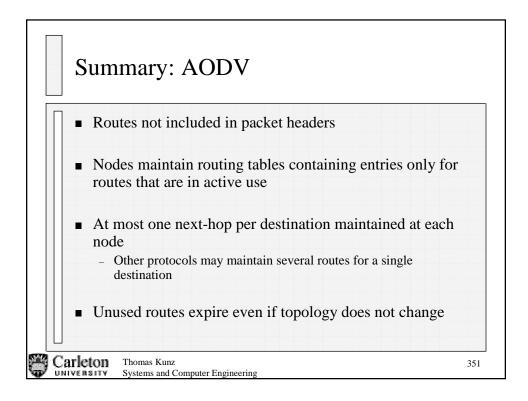


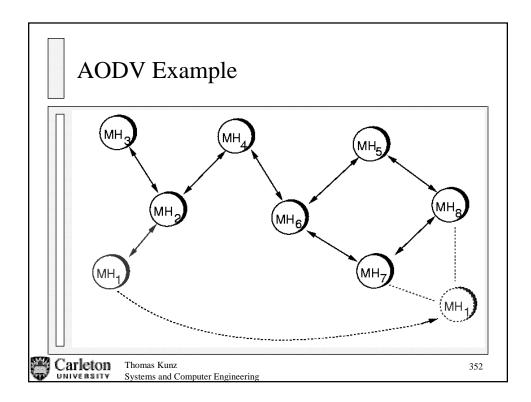


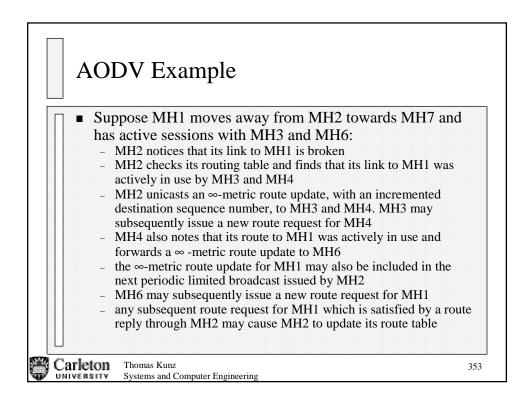


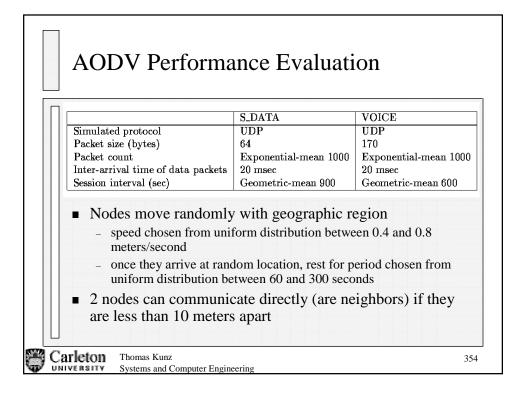




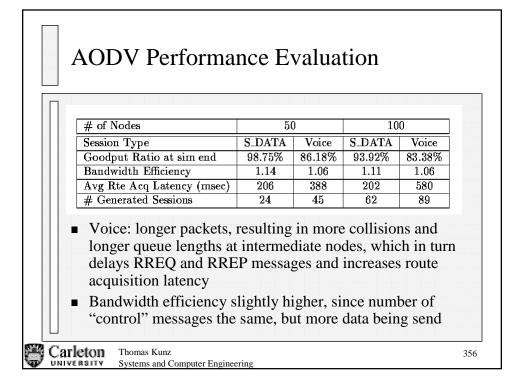


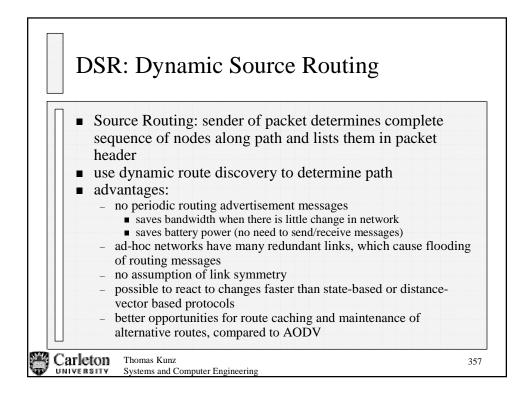


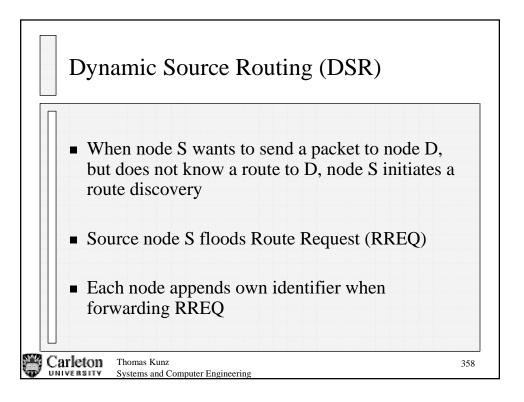


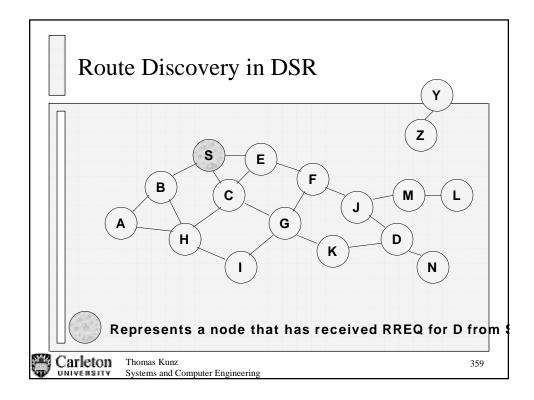


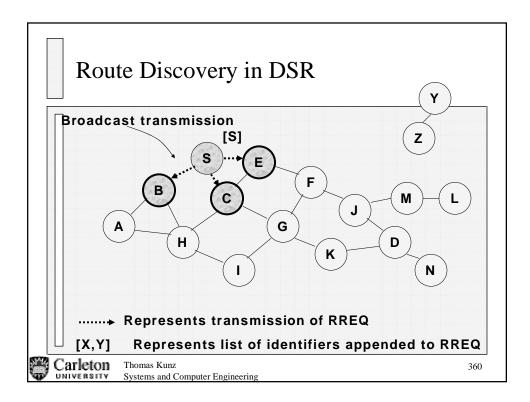
	AODV Performan	ice Ev	aluati	on	
	# of Nodes	50	100	500	1000
	Goodput Ratio at sim end	98.75%	93.92%	87.46%	70.53%
	Goodput Ratio avg	97.98%	95.91%	86.43%	72.32%
	Bandwidth Overhead Ratio	1.14	1.11	1.31	1.49
	Avg Rte Acq Latency (msec)	206	202	454	548
	Avg Path Length (hops)	3.94	4.57	6.83	10.45
	Loss to Collision	1.43%	5.74%	22.80%	26.37%
	Room Size (m)	50x50	50x50	100x100	150x150
	Simulation Length (sec)	600	600	600	300
	# Generated Sessions	24	62	172	263
	# Completed Sessions	21	46	117	120
	# Aborted Sessions	0	2	32	83
Ca	rleton Thomas Kunz				35.

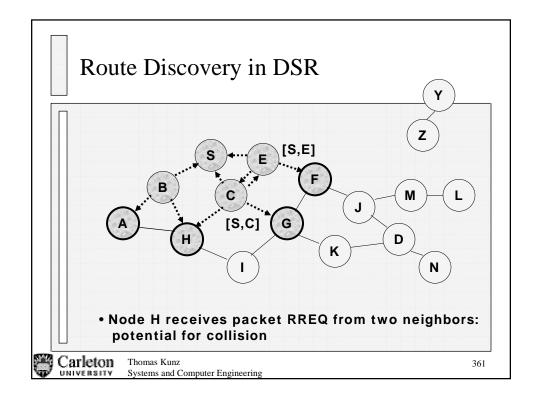


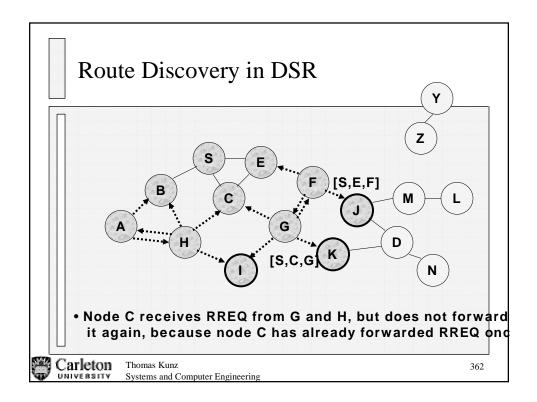


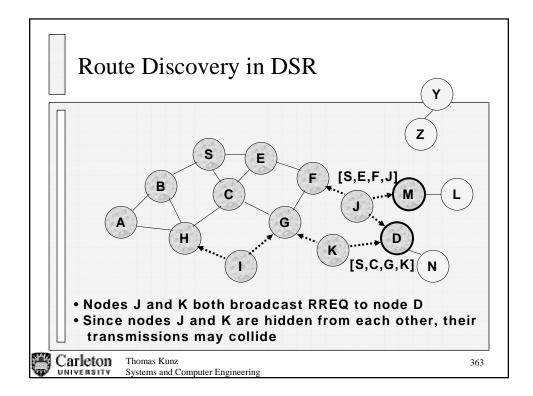


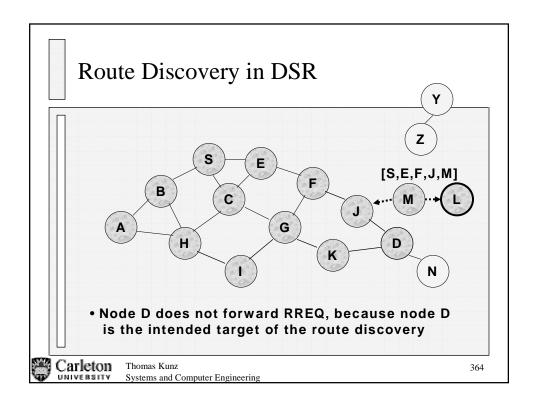


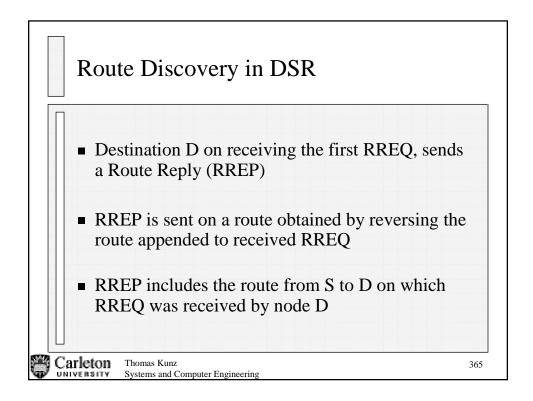


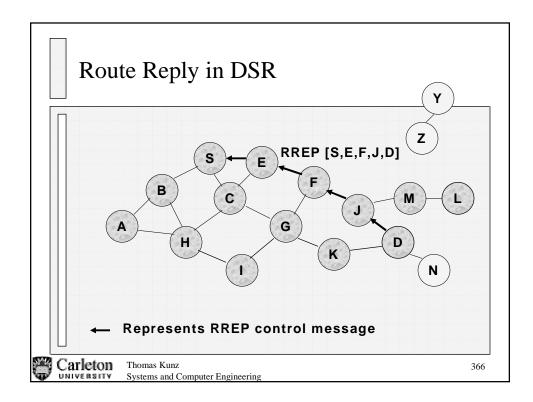


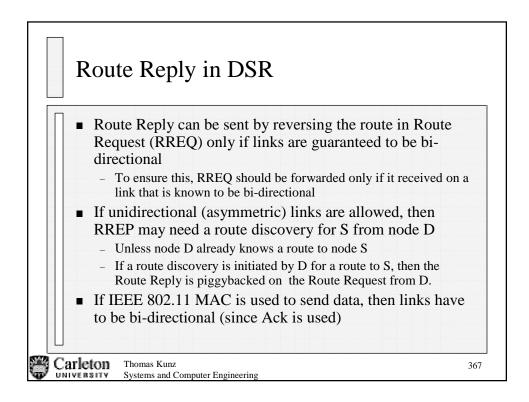


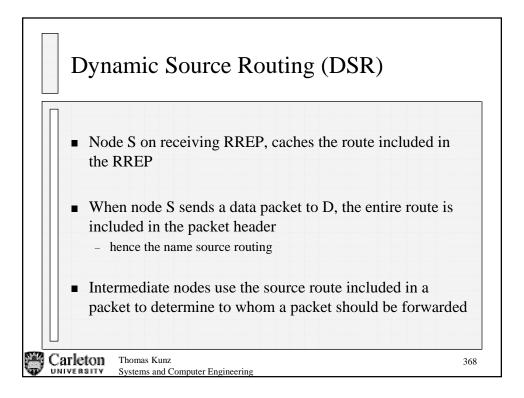


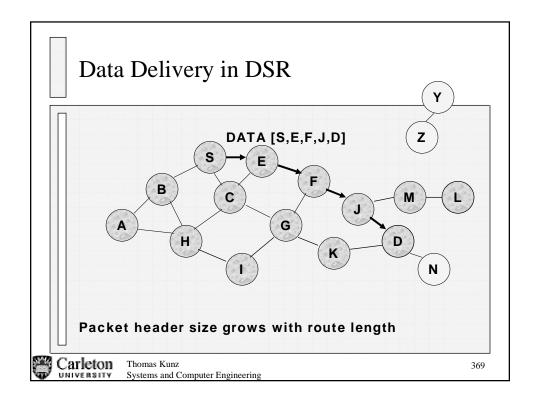


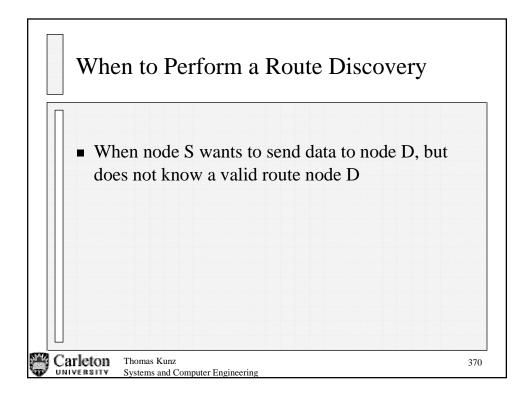


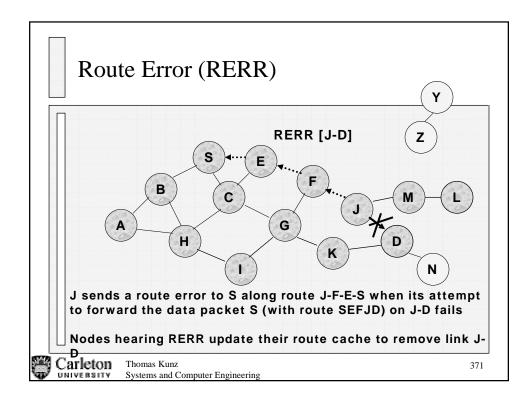


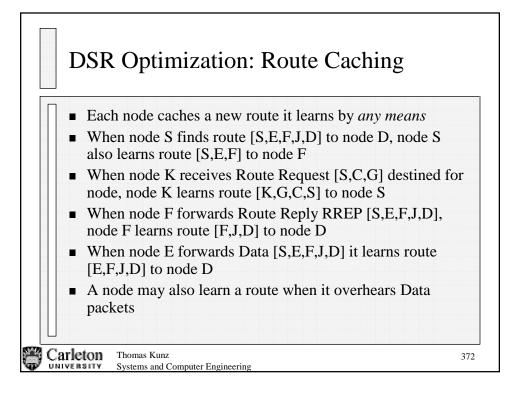


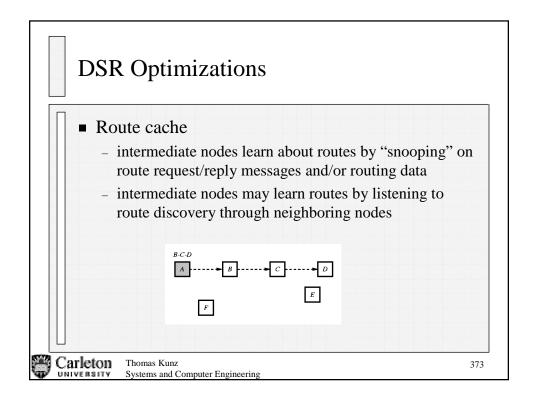


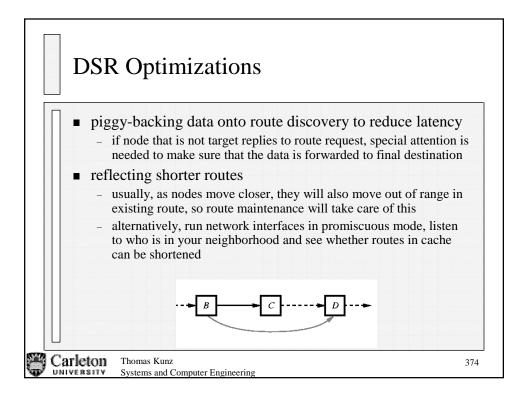


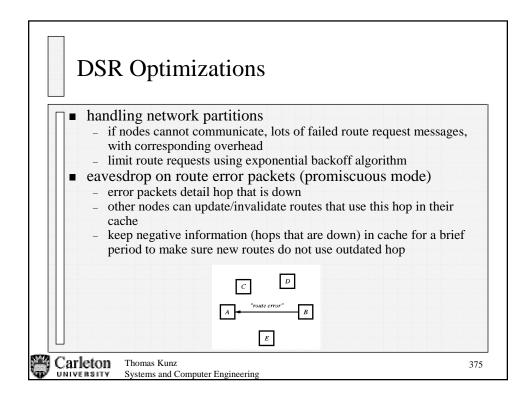


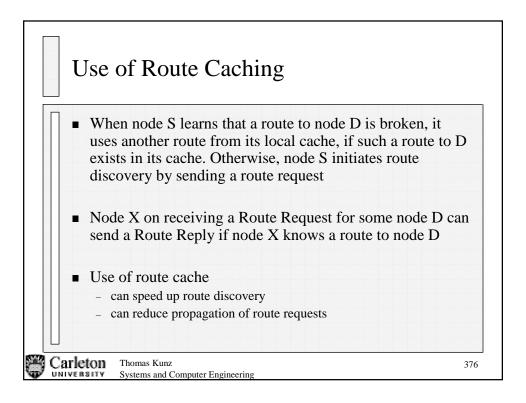


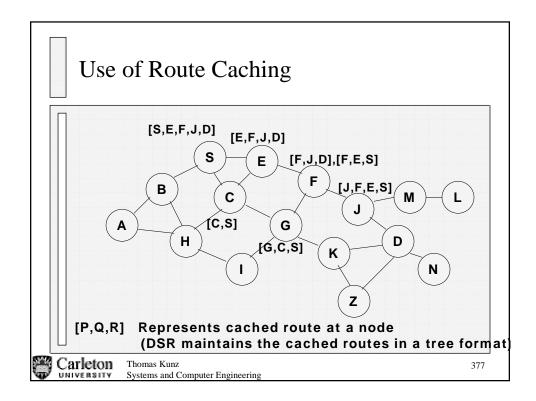


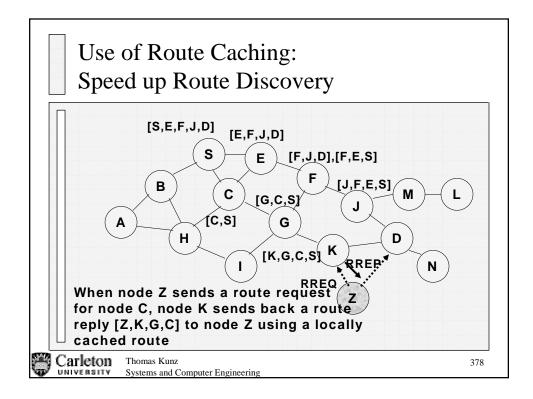


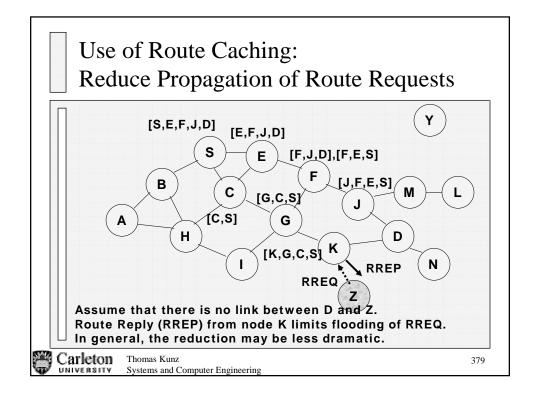


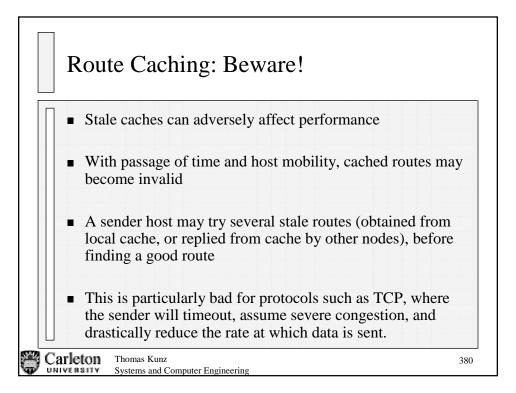


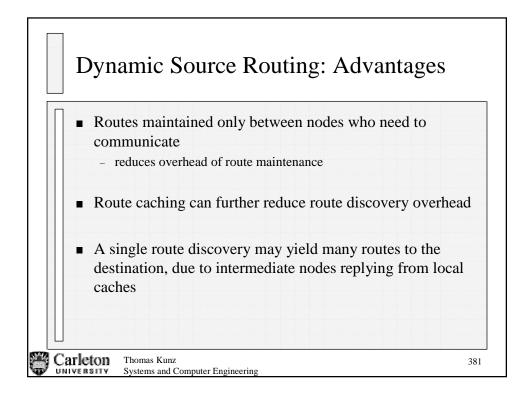


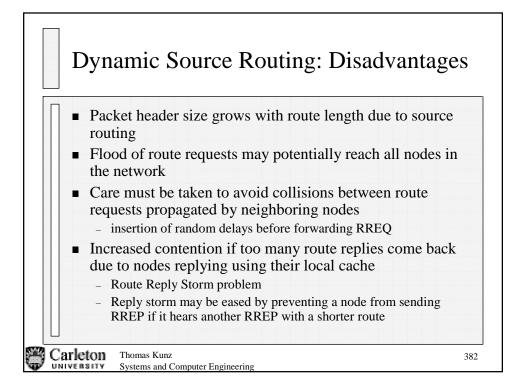


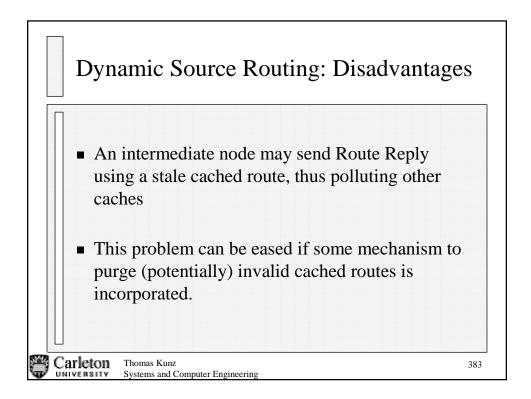


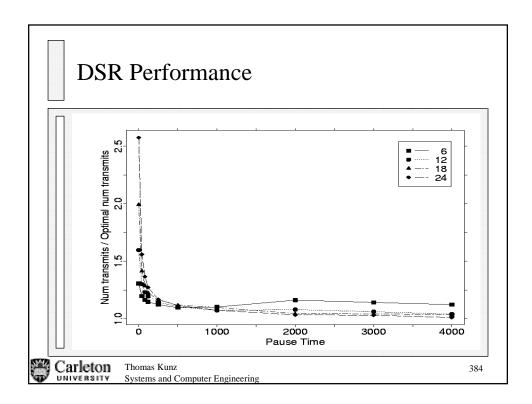


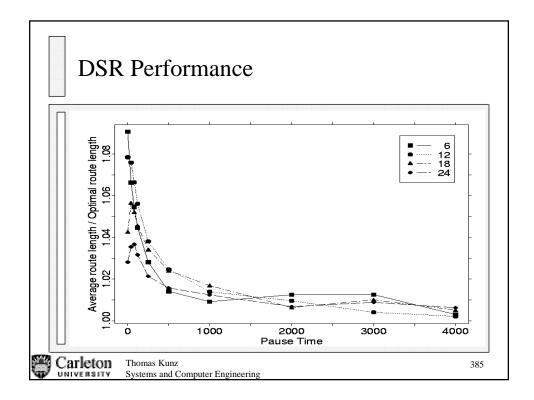


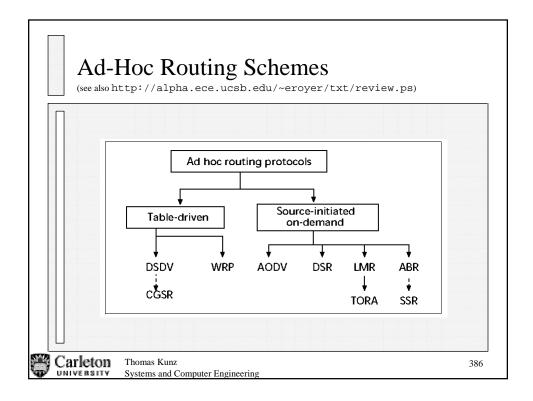




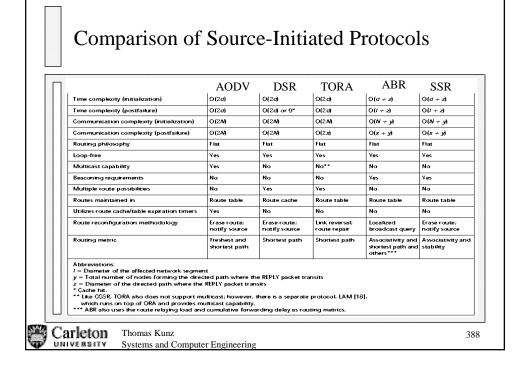


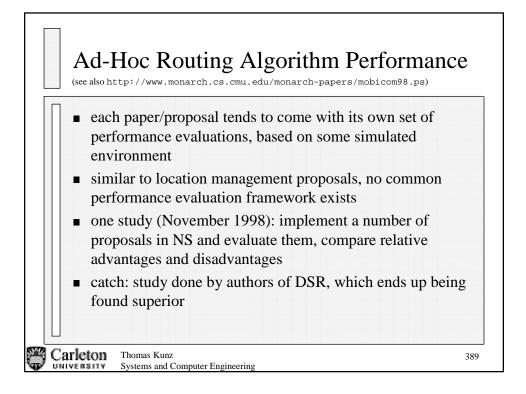


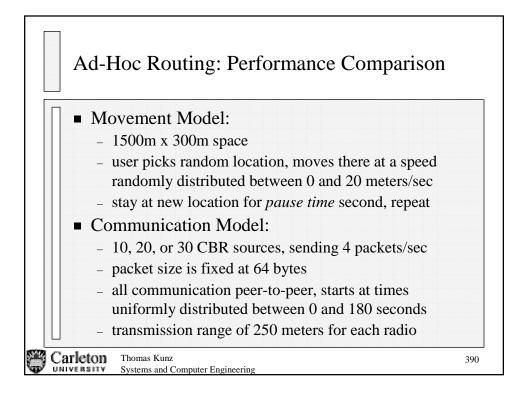


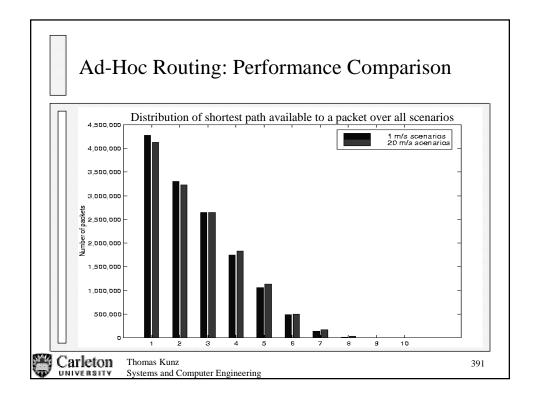


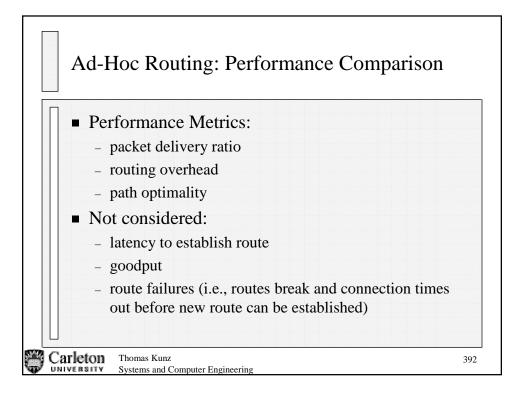
Comparison On-Demand vs. Table-Driven		
Parameters	On-Demand	Table-Drive
Availability of routing information	Available when needed	Always available regardless of need
Routing philosophy	Flat	Mostly flat, except for CGSR
Periodic route updates	Not required	Required
Coping with mobility	Use localized route discovery as in ABR and SSR	Inform other nodes to achieve a consistent routing table
Signaling traffic generated	Grows with increasing mobility of active routes (as in ABR)	Greater than that of on- demand routing
Quality of service support	Few can support QoS, although most support shortest path	Mainly shortest path as the QoS metric

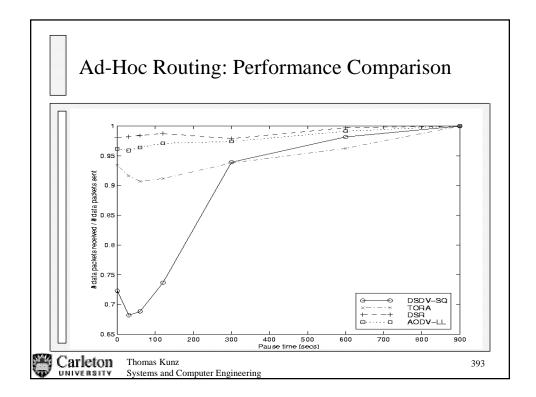


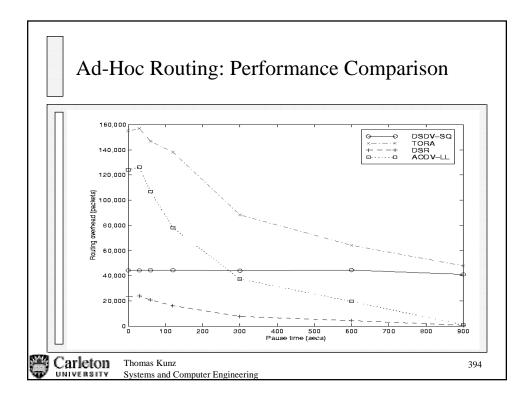


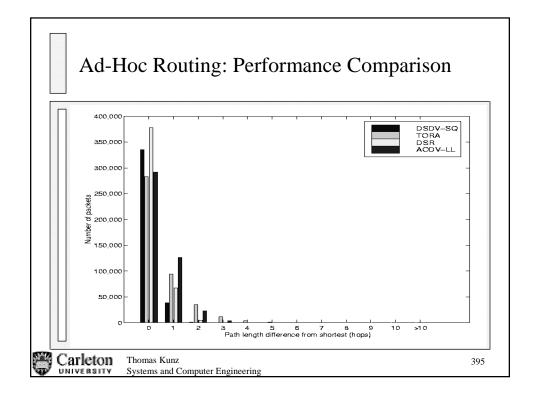


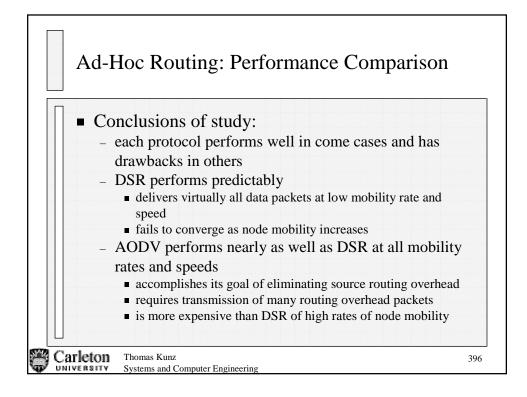


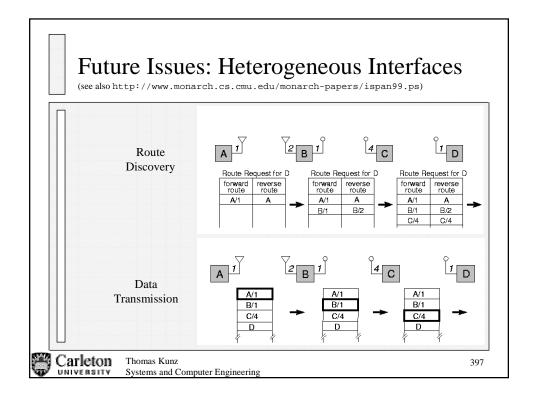


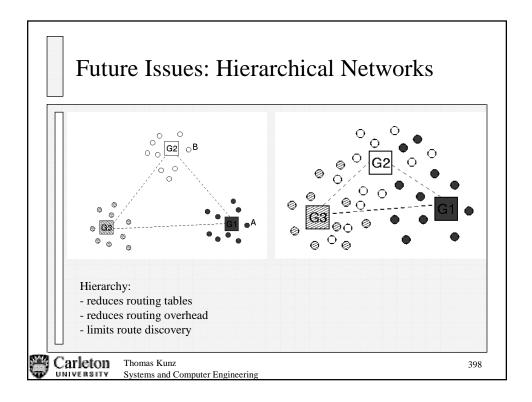


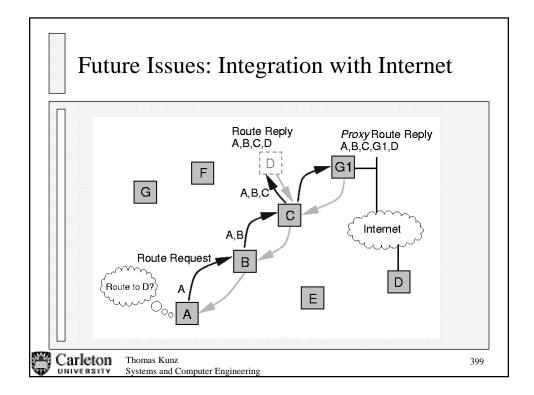


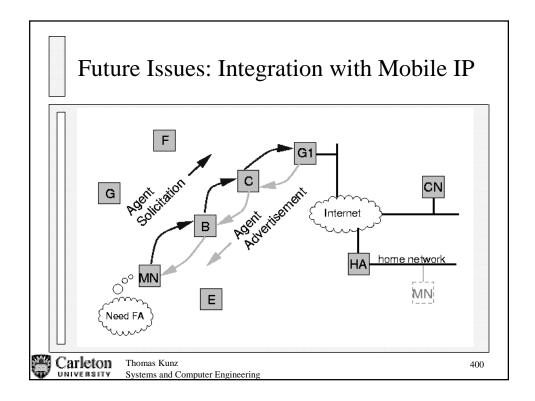


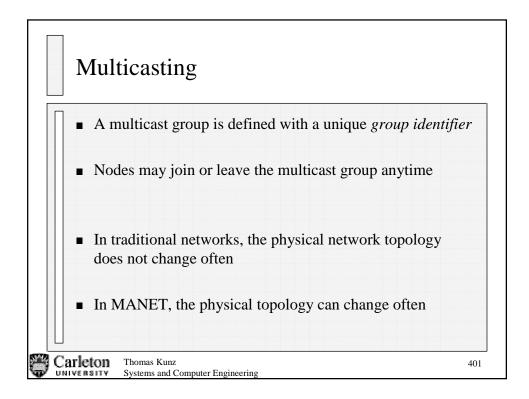


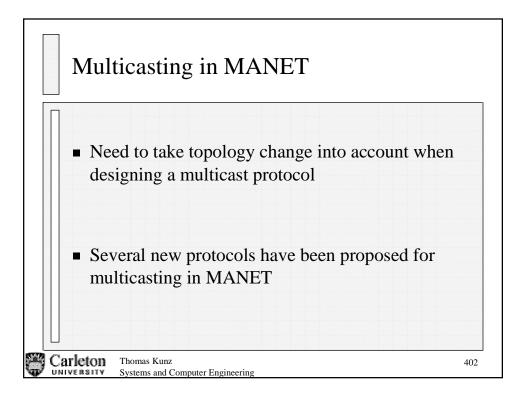


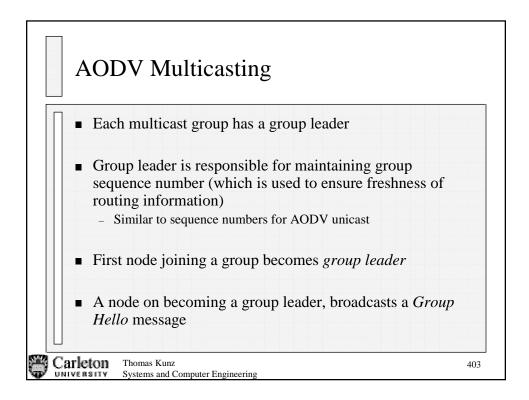


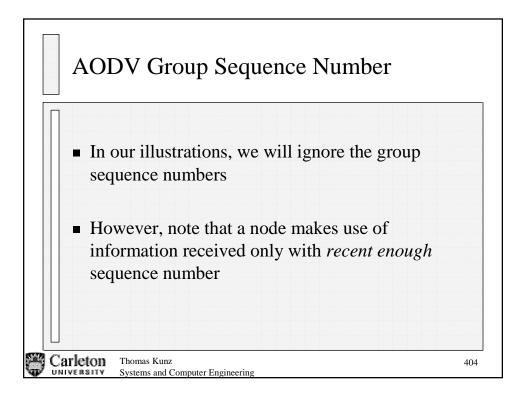


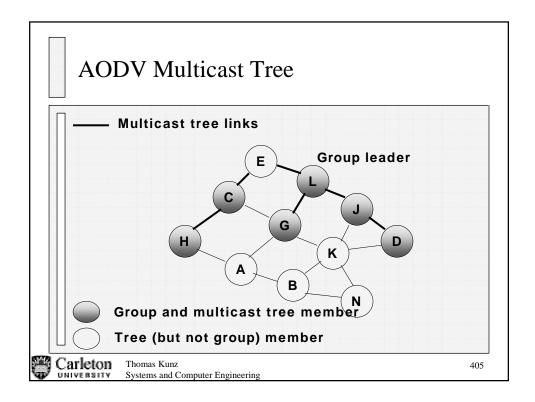


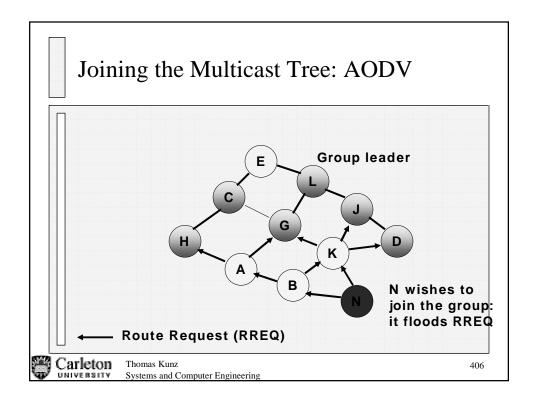


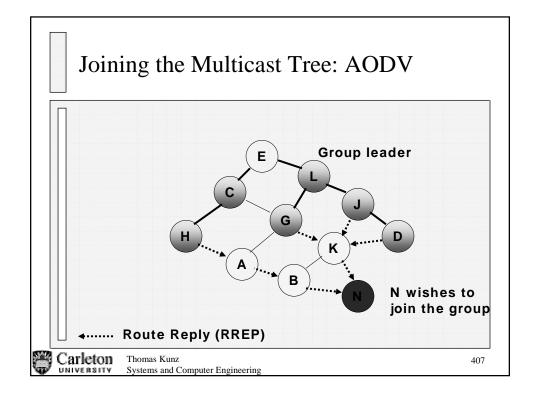


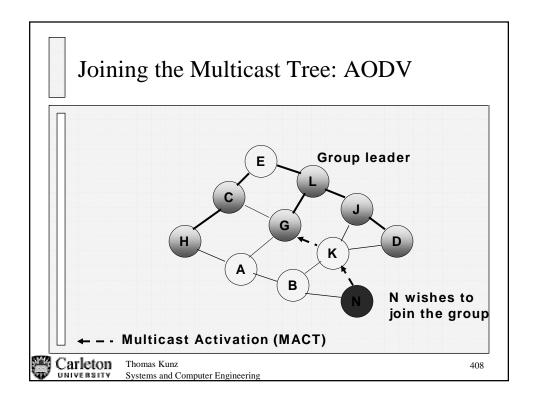


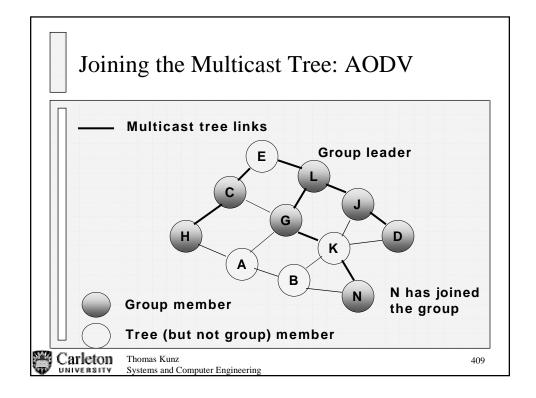


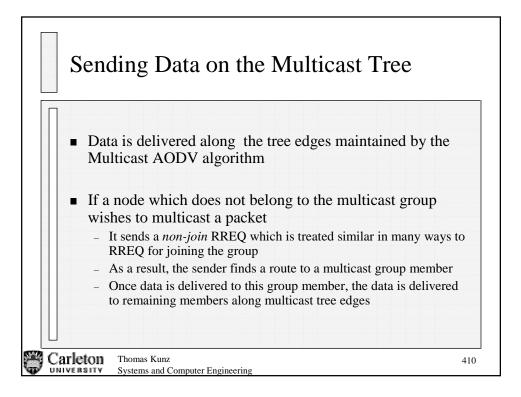


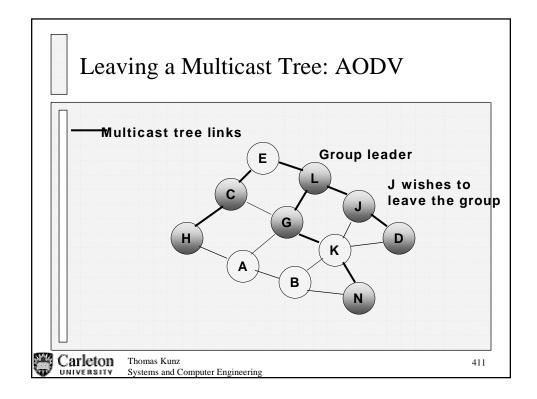


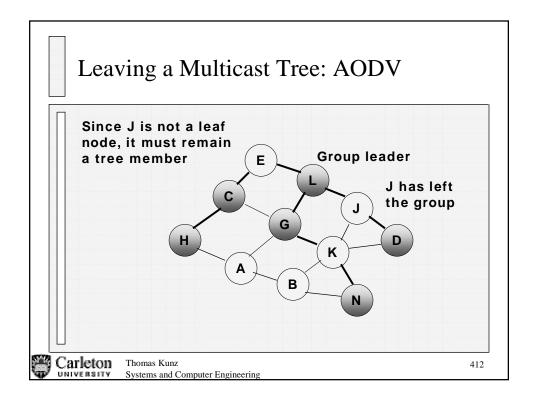


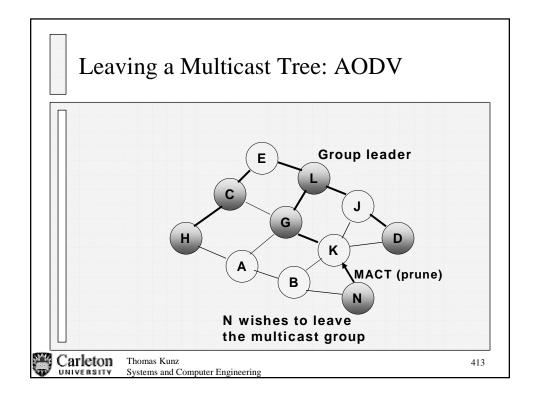


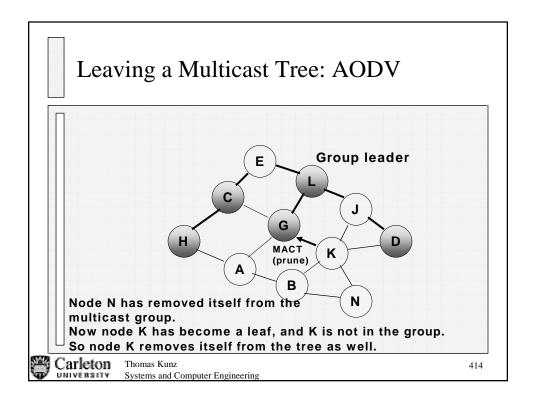


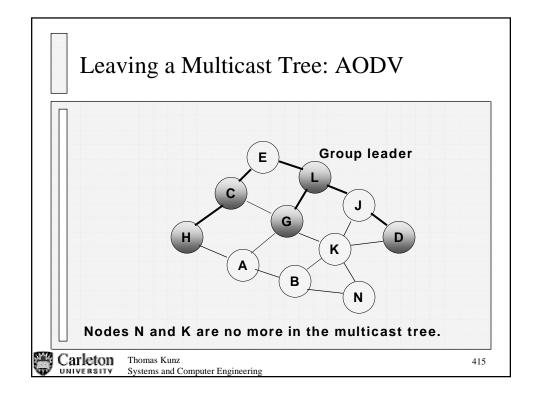








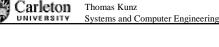






- When a link (X,Y) on the multicast tree breaks, the node that is further away from the leader is responsible to reconstruct the tree, say node X
- Node X, which is further downstream, transmits a Route Request (RREQ)
  - Only nodes which are closer to the leader than node X's last known distance are allowed to send RREP in response to the RREQ, to prevent nodes that are further downstream from node X from responding

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